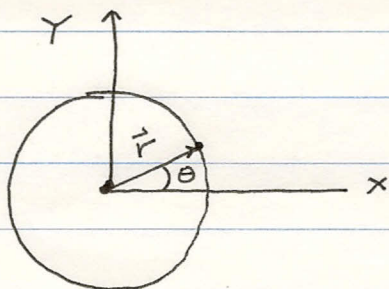


Particle on a circle



Consider a particle constrained to move on a circle of radius r . The SE is

$$-\frac{\hbar^2}{2m} \frac{d^2 \psi}{dx^2} - \frac{\hbar^2}{2m} \frac{d^2 \psi}{dy^2} = E \psi(x, y)$$

The only thing that is changing is the angle θ

so we want to write the derivatives with respect to

x and y in terms of θ .

Since $x = r \cos \theta$ & $y = r \sin \theta$

$$\cos \theta = \frac{x}{\sqrt{x^2 + y^2}} \quad \& \quad \sin \theta = \frac{y}{\sqrt{x^2 + y^2}}$$

using the chain rule

$$\frac{d\psi}{dx} = \frac{d\psi}{d\theta} \left(\frac{d\theta}{dx} \right) \quad \& \quad \frac{d\psi}{dy} = \frac{d\psi}{d\theta} \left(\frac{d\theta}{dy} \right)$$

$$\frac{\partial \theta}{\partial x} = \frac{-y}{r^2} \quad \& \quad \frac{\partial \theta}{\partial y} = \frac{x}{r^2}$$

Continuing

$$\frac{\partial^2 \psi}{\partial x^2} = \frac{\partial}{\partial x} \left(\frac{\partial \psi}{\partial \theta} \frac{\partial \theta}{\partial x} \right) = \frac{\partial \psi}{\partial \theta} \frac{\partial^2 \theta}{\partial x^2} + \left(\frac{\partial \psi}{\partial \theta} \right)^2 \frac{\partial^2 \psi}{\partial \theta^2}$$

$$\frac{\partial^2 \psi}{\partial y^2} = \frac{\partial}{\partial y} \left(\frac{\partial \psi}{\partial \theta} \frac{\partial \theta}{\partial y} \right) = \frac{\partial \psi}{\partial \theta} \frac{\partial^2 \theta}{\partial y^2} + \left(\frac{\partial \psi}{\partial \theta} \right)^2 \frac{\partial^2 \psi}{\partial \theta^2}$$

$$\text{Since } \frac{\partial^2 \theta}{\partial x^2} = \frac{-2xy}{r^4} \quad \& \quad \frac{\partial^2 \theta}{\partial y^2} = \frac{2xy}{r^4}$$

we have

$$\frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2} = \frac{1}{r^2} \frac{\partial^2 \psi}{\partial \theta^2}$$

& the Schrödinger equation becomes

$$\frac{-\hbar^2}{2Mr^2} \frac{\partial^2 \psi}{\partial \theta^2} = E \psi(\theta)$$

$$\frac{\partial^2 \psi}{\partial \theta^2} = - \frac{2Mr^2 E}{\hbar^2} \psi$$

$Mr^2 = I$, the moment of inertia

$$\text{so } \frac{\partial^2 \psi}{\partial \theta^2} = \frac{-2IE}{\hbar^2} \psi = -\omega^2 \psi(\theta)$$

$$\text{where } E = \frac{(\hbar \omega)^2}{2I}$$

$$\psi = A e^{-i\omega\theta}$$

$$\text{Boundary condition } \psi(\theta) = \psi(\theta + 2\pi)$$

$$e^{-i\omega\theta} = e^{-i\omega\theta} e^{-i\omega 2\pi}$$

requires that $\omega = 0, \pm 1, \pm 2, \dots$ integers

call these integers M

$$\psi = A e^{-iM\theta}$$

fix A by normalization. We require

$$\int_0^{2\pi} \psi^*(\theta) \psi(\theta) d\theta = 1$$

$$\text{so } A^2 2\pi = 1 \quad \& \quad A = \frac{1}{\sqrt{2\pi}}$$

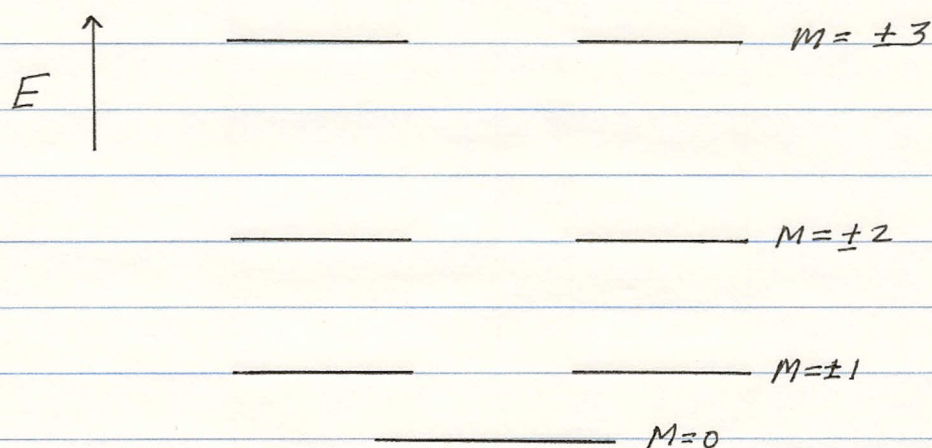
$$\therefore \psi_M(\theta) = \frac{1}{\sqrt{2\pi}} e^{-iM\theta} \quad M = 0, \pm 1, \pm 2, \dots$$

The energy levels in this system are

$$E_M = \frac{\hbar^2 M^2}{2I} ; M = 0, \pm 1, \pm 2, \dots$$

Note that the lowest energy is non degenerate

& equals 0, while the others are each doubly degenerate



The probability of finding the particle in the interval $d\theta$ around the point θ is given by

$$\psi_M^*(\theta) \psi_M(\theta) d\theta = \frac{1}{2\pi} e^{iM\theta} e^{-iM\theta} d\theta = \frac{d\theta}{2\pi}$$

& there is a uniform probability of finding the particle anywhere along the circle.

The linear momentum of this particle is a vector
with a x & y component

$$\hat{\vec{P}} = \hat{x} \frac{\hbar}{i} \frac{\partial}{\partial x} + \hat{y} \frac{\hbar}{i} \frac{\partial}{\partial y}$$

since $\frac{\partial \psi}{\partial x} = \frac{\partial \psi}{\partial \theta} \frac{\partial \theta}{\partial x} = -\frac{y}{r^2} \frac{\partial \psi}{\partial \theta}$

& $\frac{\partial \psi}{\partial y} = \frac{\partial \psi}{\partial \theta} \frac{\partial \theta}{\partial y} = +\frac{x}{r^2} \frac{\partial \psi}{\partial \theta}$

we can write this operator as

$$\hat{\vec{P}} = \frac{\hbar}{i r^2} (-y \hat{x} + x \hat{y}) \frac{\partial}{\partial \theta}$$

recall that the angular momentum is given by

$$\vec{L} = \vec{r} \times \vec{P} \quad \text{so, the angular momentum}$$

operator is

$$\hat{\vec{L}} = \frac{\hbar}{i r^2} \vec{r} \times (-y \hat{x} + x \hat{y}) \frac{\partial}{\partial \theta}$$

$$\& \quad \vec{r} \times (-y \hat{x} + x \hat{y}) = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ x & y & 0 \\ -y & x & 0 \end{vmatrix}$$

$$\text{so } \vec{r} \times (-y\hat{x} + x\hat{y}) = (x^2 + y^2)\hat{z} = r^2\hat{z}$$

≠ so

$$\hat{L} = \hat{z} \frac{\hbar}{i} \frac{\partial}{\partial \theta}$$

$$\neq \frac{\hbar}{i} \frac{\partial}{\partial \theta} = \hat{L}_z \quad (\text{the } z \text{ component of the angular momentum})$$

note the expectation value of $\hat{L}_z$

$$\langle \hat{L}_z \rangle = \frac{1}{2\pi} \int_0^{2\pi} e^{+im\theta} \cdot \frac{\hbar}{i} \frac{\partial}{\partial \theta} e^{-im\theta} d\theta$$

$$= \frac{\hbar}{2\pi i} (-im) 2\pi = -m\hbar \text{ or } m\hbar \text{ since}$$

$$M = 0, \pm 1, \pm 2, \dots$$