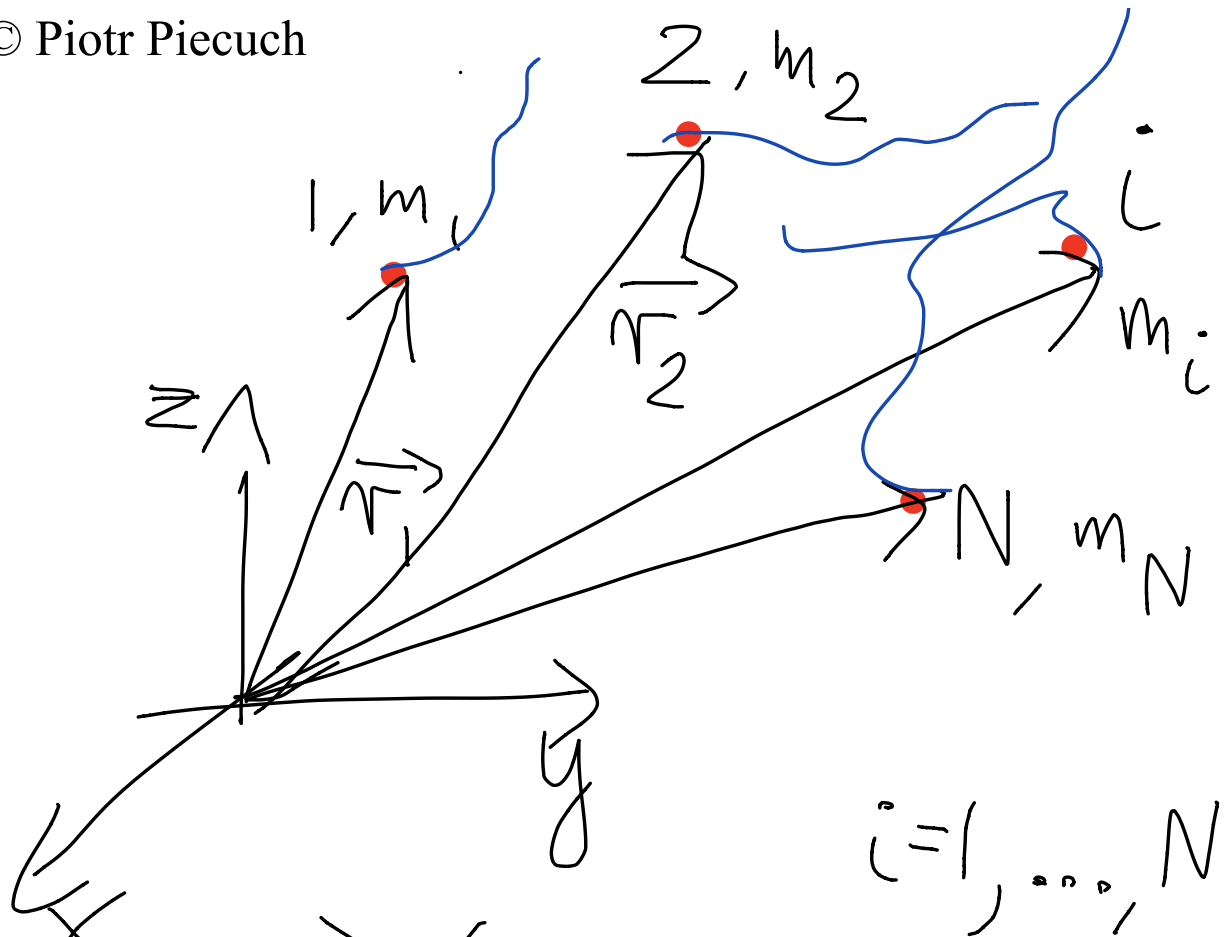


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$$\vec{r}_1 = (x_1, y_1, z_1)$$

$$\vec{r}_2 = (x_2, y_2, z_2)$$

$$\vec{r}_i = (x_i, y_i, z_i)$$

$$\vec{r}_N = (x_N, y_N, z_N)$$

$$m_i \frac{d^2 \vec{r}_i}{dt^2} = \vec{F}_i, \quad i=1, \dots, N$$

$$\vec{F}_i = (F_{xi}, F_{yi}, F_{zi})$$

$$\vec{F}_i = \vec{F}_i(\vec{r}_1, \dots, \vec{r}_N,$$

$$\vec{r}_1, \dots, \vec{r}_N, t)$$

$$\dot{\vec{r}}_i = \frac{d\vec{r}_i}{dt}, \quad \ddot{\vec{r}}_i = \frac{d^2 \vec{r}_i}{dt^2}$$

$$m_i \ddot{\vec{r}}_i = \vec{F}_i$$

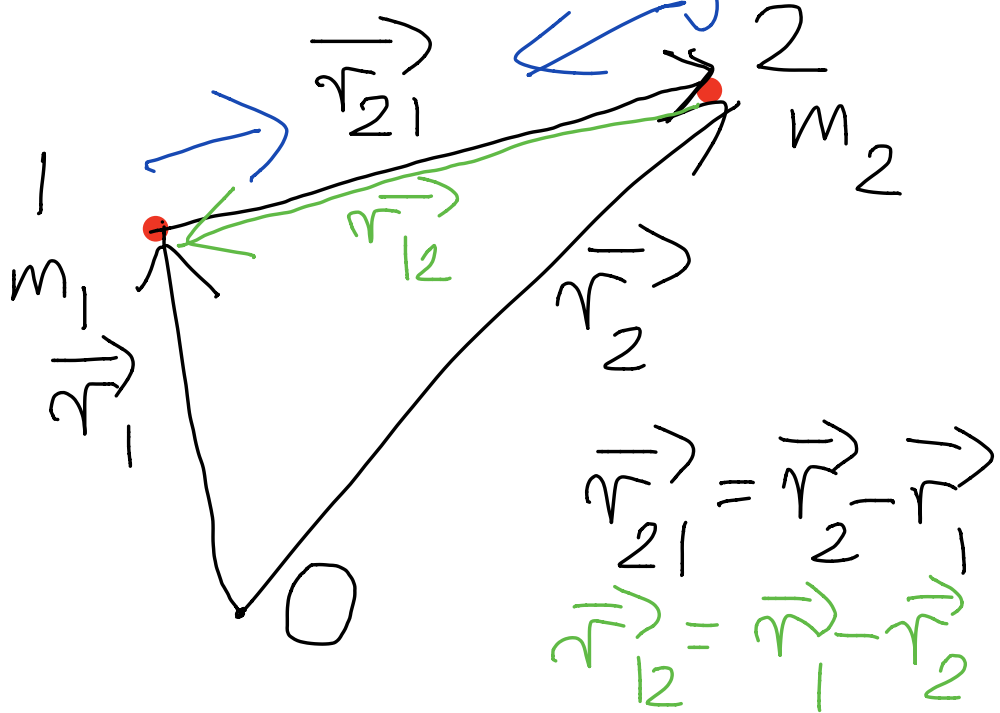
$$i = 1, \dots, N$$

$$\vec{r}_{i0} = \vec{r}_i(t_0)$$

$$\vec{v}_{i0} = \dot{\vec{r}}_{i0} = \dot{\vec{r}}_i(t_0)$$

$$i = 1, \dots, N$$

Gravitational force



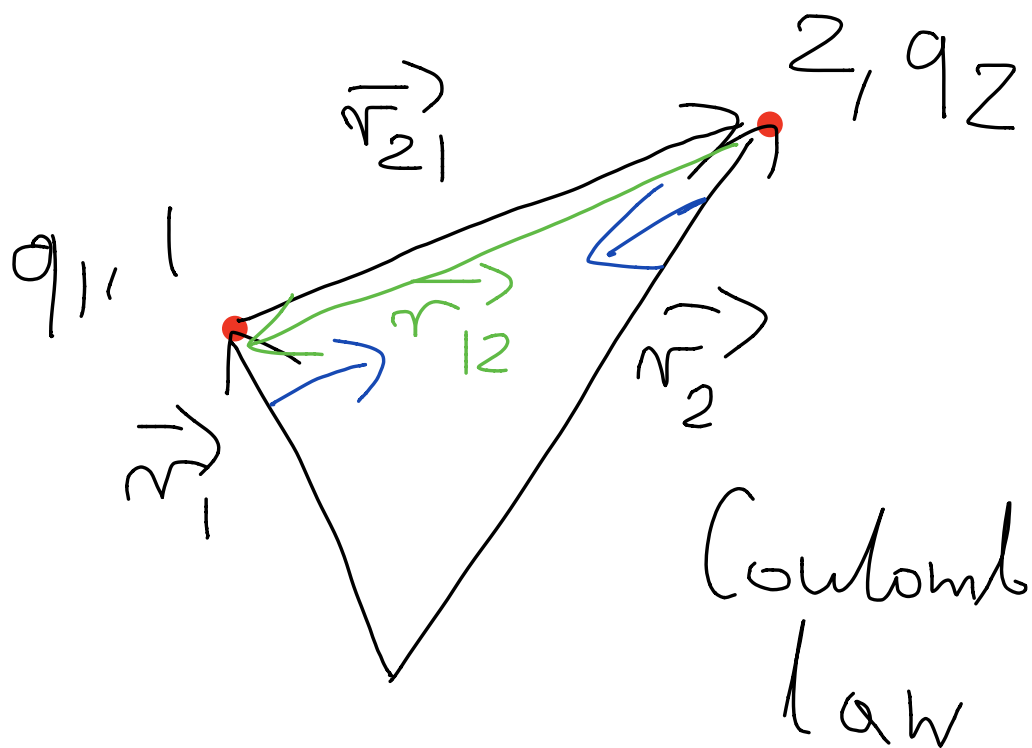
$$\vec{r}_{21} = \vec{r}_2 - \vec{r}_1$$

$$\vec{r}_{12} = \vec{r}_1 - \vec{r}_2$$

$$\vec{F}_{12} = -\vec{F}_{21}$$

$$= -G \frac{m_1 m_2}{r_{12}^2} \frac{\vec{r}_{12}}{r_{12}}$$

on 1
due to 2



$$\vec{F}_{21} = -\vec{F}_{12}$$

$$= + \frac{q_1 q_2}{r_{12}^2} \frac{\vec{r}_{12}}{r_{12}}$$

$$q_1 q_2 > 0$$

$$q_1 q_2 < 0$$

Lorentz force

$$\vec{E} = \vec{E}(\underbrace{x, y, z}_{\vec{r}}, t)$$

$$\vec{B} = \vec{B}(\underbrace{x, y, z}_{\vec{r}}, t)$$

Maxwell

$$\vec{F} = q \left[\vec{E} + \frac{1}{c} \underbrace{\vec{v}}_{\vec{v}} \times \vec{B} \right]$$

$$m_i \vec{r}_i = \vec{r}_i / \sum_{i=1}^N$$

$$\sum_{i=1}^N m_i \vec{r}_i = \sum_{i=1}^N \vec{r}_i$$

$$\sum_{i=1}^N \vec{r}_i = \sum_{i=1}^N \vec{r}_i^{\text{ext}} = \vec{r}^{\text{ext}}$$

$$+ \sum_{i=1}^N \sum_{j(\neq i)}^N \vec{r}_{ij}$$

$$\sum_i \vec{F}_i = \vec{F}_{\text{ext}}$$

$$+ \frac{1}{2} \sum_{i,j} \delta_{ij} \vec{F}_{ij} + \sum_{j,i} \delta_{ji} \vec{F}_{ij}$$

$$\sum_{i,j} \delta_{ij} \vec{F}_{ij}$$

$$= \vec{F}_{\text{ext}} + \frac{1}{2} \sum_{i,j} \left(\underbrace{\vec{F}_{ij} + \vec{F}_{ji}}_{=0} \right)$$

$$\sum_{i=1}^N m_i \vec{r}_i = \vec{F}_{ext}$$

$$\frac{d}{dt} \sum_{i=1}^N (m_i \vec{r}_i) = \vec{F}_{ext}$$

$$m_i \vec{r}_i = \vec{p}_i$$

$$\frac{d}{dt} \left(\sum_{i=1}^N \vec{p}_i \right) = \vec{F}_{ext}$$

$$\downarrow$$

$$\vec{P}$$

$$\frac{d\vec{P}}{dt} = \vec{F}_{\text{ext}}$$

$$\text{If } \vec{F}_{\text{ext}} = 0 \Rightarrow$$

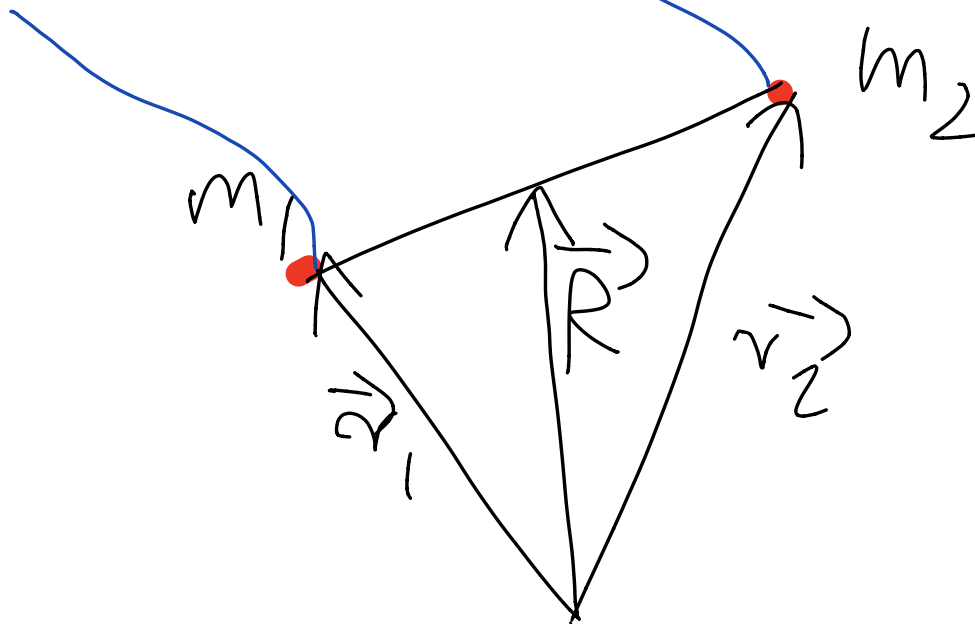
$$\frac{d\vec{P}}{dt} = 0 \Rightarrow$$

$$\Rightarrow \vec{P} = \text{const}$$

$$\sum_{i=1}^N m_i \vec{v}_i = \sum_{i=1}^N \vec{p}_i = \text{const.}$$

$$\vec{R} = \frac{\sum_{i=1}^N m_i \vec{r}_i}{M} \quad \text{COM}$$

$$M = \sum_{i=1}^N m_i$$



$$\vec{R} = \frac{\sum_{i=1}^N m_i \vec{r}_i}{M}$$

$$M \vec{R} = \sum_{i=1}^N m_i \vec{r}_i = \vec{P}$$

$$\text{If } \vec{F}_{\text{ext}} = 0$$

$$\Rightarrow \vec{P} = \text{const.}$$

$$\Rightarrow \dot{\vec{R}} = \text{const.}$$

$$\frac{d\vec{R}}{dt} = \text{const.}$$

$$\vec{R}(t) = \vec{R}(t_0) + \vec{R}'(t_0)(t - t_0)$$

$$\frac{d\vec{L}}{dt} = \vec{D}$$

$$\vec{D} = \sum_{i=1}^N (\vec{r}_i \times \vec{F}_i)$$

$$\vec{L} = \sum_{i=1}^N (\vec{r}_i \times \vec{p}_i)$$

$$\vec{F}_i = \vec{F}_i^{\text{ext}} + \sum_j \vec{F}_{ij}$$

$$\vec{D} = \sum_{i=1}^N (\vec{r}_i \times \vec{F}_i^{\text{ext}})$$

$$+ \sum_{i,j=1}^N (\vec{r}_i \times \vec{F}_{ji})$$

$$= \vec{D}^{\text{ext}} + \frac{1}{2} \sum_{i,j=1}^N (\vec{r}_i \times \vec{F}_{ji})$$

$$+ \sum_{i,j=1}^N (\vec{r}_i \times \vec{F}_{ij})$$

$$\vec{D} = \vec{D}_{\text{ext}}$$

$$+ \frac{1}{2} \sum_{ij} (\vec{r}_i - \vec{r}_j) \times \vec{f}_{ji}$$

$$= \frac{1}{2} \sum_{ij} \vec{r}_{ij} \times \vec{f}_{ji}$$

$$\vec{r}_{ij} \times \vec{f}_{ji} = \vec{r}_{ji} \times \vec{f}_{ij}$$

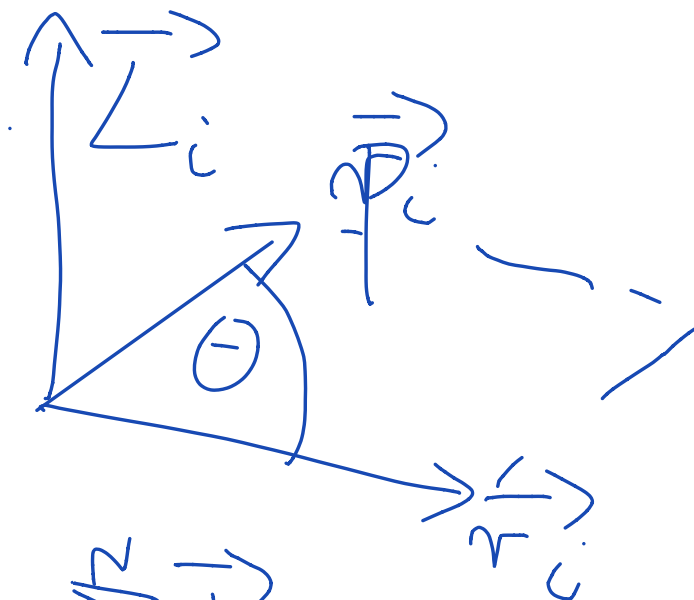
$$\frac{d\vec{L}}{dt} = \vec{D} = \vec{D}_{\text{ext}}$$

$$= \sum_{i=1}^N \vec{r}_i \times \vec{f}_i$$

$$\text{If } \vec{D}_{\text{ext}} = 0 \Rightarrow$$

$$\Rightarrow \frac{d\vec{L}}{dt} = 0 \Rightarrow \vec{L} = \text{const}$$

$$\vec{L} = \sum_{i=1}^N \vec{r}_i \times \vec{p}_i$$



$$\vec{Z} = \sum_{i=1}^N \vec{Z}_i$$

$$\|\vec{Z}_i\| = L_i = r_i p_i \times \sin(\theta)$$

$$m_i \ddot{x}_i = F_i, \quad i=1, \dots, N$$

$$m_j \ddot{x}_j = X_j, \quad j=1, \dots, 3N$$

$$\cancel{X_j} \quad \cancel{m_j}$$

$$\sum_{j=1}^{3N} m_j \ddot{x}_j \ddot{x}_j$$

$$= \sum_{j=1}^{3N} X_j \ddot{x}_j$$

$$\sum_{j=1}^{3N} m_j \dot{x}_j \dot{x}_j$$

$$\frac{1}{2} \frac{d}{dt} (\dot{x}_j^2)$$

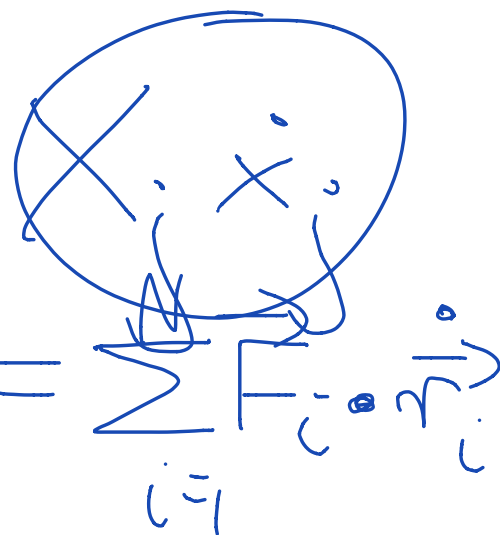
$$= \cancel{\frac{1}{2}} \dot{x}_j \ddot{x}_j = \dot{x}_j \ddot{x}_j$$

$$\frac{1}{2} \frac{d}{dt} \left[\sum_{j=1}^{3N} m_j (\dot{x}_j)^2 \right]$$

$T \rightarrow$ kinetic energy

$$T = \frac{1}{2} \sum_{j=1}^{3N} m_j \dot{x}_j^2$$

$$= \frac{1}{2} \sum_{i=1}^{20} m_i (\dot{\vec{r}}_i)^2$$

$$\frac{dT}{dt} = \sum_{j=1}^{3N} \left(\vec{F}_j \cdot \vec{x}_j \right)$$


$$\begin{aligned}\vec{a} \cdot \vec{b} &= a_x b_x + a_y b_y \\ &\quad + a_z b_z \\ &= \|\vec{a}\| \|\vec{b}\| \cos \theta\end{aligned}$$

$$\int_{t_0}^{t_1} \frac{dW}{dt} dt =$$

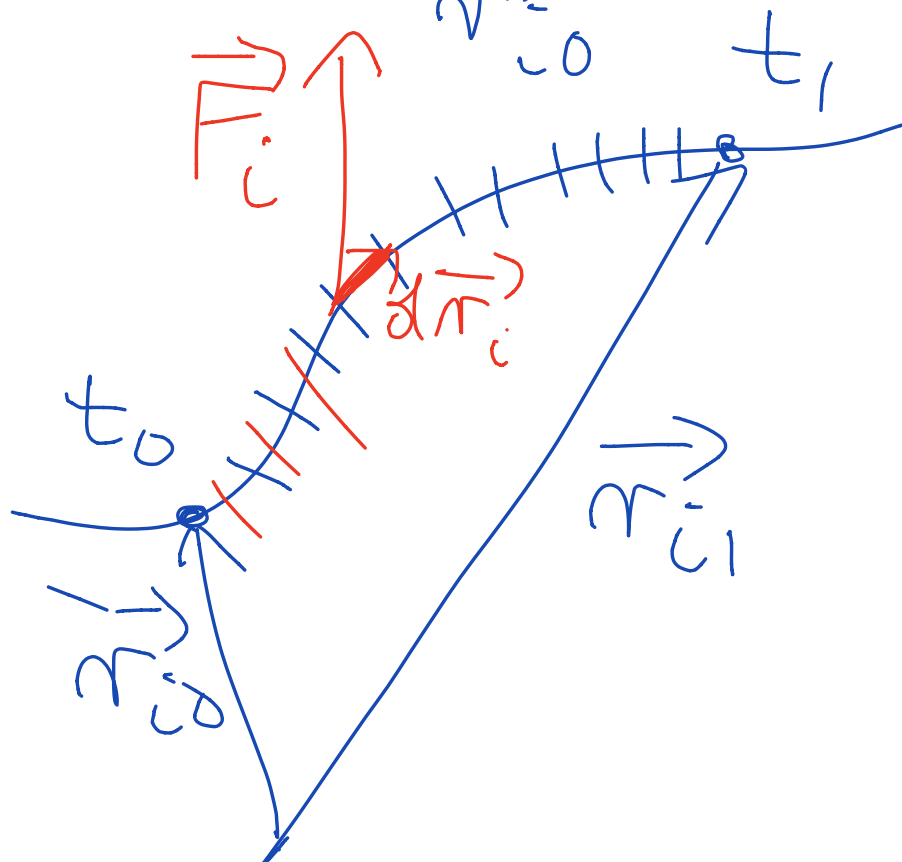
$\vec{F}_i$
 $d\vec{r}_i$

$$= \sum_{i=1}^N \int_{t_0}^{t_1} \underbrace{(\vec{F}_i \cdot \dot{\vec{r}}_i)}_{\text{work}} dt$$

$\dot{\vec{r}}_i$
 $d\vec{r}_i$

$$T(t_1) - T(t_0) = \left[\sum_{i=1}^N \vec{F}_i \cdot d\vec{r}_i \right]$$

work



derived from
potential

Assume that our
forces irrotational

$$V = V(\vec{r}_1(t), \dots, \vec{r}_N(t), t)$$

potential function

$$-\nabla_i V = \vec{F}_i$$

$$\nabla_i = \left(\frac{\partial}{\partial x_i}, \frac{\partial}{\partial y_i}, \frac{\partial}{\partial z_i} \right)$$

$$\vec{F}_i = -\nabla_i V$$

$$\vec{x}_j = -\frac{\partial V}{\partial x_j}$$

$j=1, \dots, 3N$

$$\frac{dV}{dt} = \sum_{j=1}^{3N} \frac{\partial V}{\partial x_j} \left(\frac{dx_j}{dt} \right)$$

+ $\frac{\partial V}{\partial t}$

Assume that

$$\boxed{\frac{\partial V}{\partial t} = 0}$$

Conservative

$$\begin{aligned} \frac{dV}{dt} &= \sum_{j=1}^{3N} \boxed{\frac{\partial V}{\partial x_j}} \dot{x}_j \\ &= - \sum_{j=1}^{3N} \dot{x}_j x_j \end{aligned}$$

$$W_{\text{work}} = \sum_{j=1}^{3N} \int_{t_0}^{t_1} \mathbf{X}_j \cdot \dot{\mathbf{x}}_j dt$$

$$= - \int_{t_0}^{t_1} \frac{dV}{dt} dt$$

$$= - [V(t_1) - V(t_0)]$$

$$= T(t_1) - T(t_0)$$

$$T(t_0) + V(t_0)$$

$$= T(t_1) + V(t_1)$$

$$= \text{const.}$$

$$= E$$

energy

$$E = T + V$$

$$\begin{aligned}
 V(t_1) - V(t_0) &= \sum_i \int_{t_0}^{t_1} \vec{F}_i \cdot d\vec{r}_i \\
 &= \sum_i \int_{t_0}^{t_1} \vec{F}_i \cdot \vec{v}_i dt \\
 &= \text{work}
 \end{aligned}$$