## Week 4: Chap. 3 Statistics of Radioactivity

## Vacuum Technology

General use of Statistical Distributions in Radiation Measurements
-- Fluctuations in Number
--- distribution function models
-- Fluctuations in Time

General Detector Properties

"Without deviation from the norm, progress is not possible." Frank Zappa, 1986

## Chap. 3 Statistics \& Measurement

Fact: Randomness of decay leads to statistical fluctuations.
Goals:
(I) Characterization of fluctuations in data: The problem is: A set of measurements of one quantity contains a range of answers. How should we describe the set ? [could enumerate a small set: $\{7,12,15,11\}, 11.25+/-3.3$ ]

Experimental Mean: $\quad \overline{x_{e}}=\frac{1}{N} \sum_{1}^{N} x_{i}$
Experimental Residuals: $\quad d_{i}=x_{i}-\overline{x_{e}}$ note $\sum_{1}^{N} d_{i}=0$
Deviation from (the) mean $\quad \varepsilon_{i}=x_{i}-\bar{x} \quad \sigma^{2}=\overline{\varepsilon^{2}}=\frac{1}{N} \sum_{1}^{N}\left(x_{i}-\bar{x}\right)^{2}$
And (the) variance:

$$
\sigma^{2}=\overline{\varepsilon^{2}}=\frac{1}{N} \sum_{1}^{N}\left(x_{i}-\bar{x}\right)^{2}
$$

Expt. Sample Variance:

$$
s^{2}=\frac{1}{N-1} \sum_{1}^{N}\left(\overline{x_{e}}-x_{i}\right)^{2} \quad \text { practical expresssion } \quad s^{2} \approx \overline{x_{i}^{2}}-\left(\overline{x_{e}}\right)^{2}
$$

## Statistics \& Measurement - Models -1-

(II) Fluctuation Models:
A) The binomial distribution, a theory with three general parameters (a,b,n)
$(a+b)^{n}=a^{n} / 0!+\left(n a^{n-1} b^{1}\right) / 1!+\left[n(n-1) a^{n-2} b^{2}\right] / 2!+\ldots\left[n!a^{n-x} b^{x}\right] /(n-x)!x!+b^{n} / 0!$
Special case of a fractional probability, p , which allows one variable to be removed,
$\mathrm{b}=\mathrm{p}, \quad \mathrm{a}=1-\mathrm{p}$ so that $\mathrm{a}+\mathrm{b}=1$ and automatically normalizes the distribution:

$$
(\mathrm{a}+\mathrm{b})^{\mathrm{n}}=\sum \mathrm{P}_{\mathrm{n}}(\mathrm{x})=(1-\mathrm{p})^{\mathrm{n}}+\ldots\left[\mathrm{n}!(1-\mathrm{p})^{\mathrm{n}-\mathrm{x}} \mathrm{p}^{\mathrm{x}}\right] /(\mathrm{n}-\mathrm{x})!\mathrm{x}!\ldots+\mathrm{p}^{\mathrm{n}}
$$

Thus, if " p " is the probability of success and " n " is the number of tries, then x can be seen to be the number of successes.

Example 1: Coin flip: $p=1 / 2 \quad(1-p)=1 / 2$

Example 2: Toss die: $p=1 / 6 \quad(1-p)=5 / 6$



Example 3: (fractional) Probability of radioactive decay:

$$
\mathrm{p}=(\# \text { decay }) /(\# \text { sample })=\left(\mathrm{N}_{0}-\mathrm{N}\right) / \mathrm{N}_{0}=\left(1-\mathrm{e}^{-\lambda \mathrm{t}}\right) ;(1-\mathrm{p})=\mathrm{e}^{-\lambda \mathrm{t}}
$$

(C) DJMorrissey, 2019

Statistics \& Measurement - Models -2-
(II) Fluctuation Models:
A) Binomial distribution function (theory),
special case: $n$ tries with $p$ fractional probability, gives $x$ successes

$$
\begin{aligned}
& \mathrm{P}_{\mathrm{n}}(\mathrm{x})=\quad[\mathrm{n}!/(\mathrm{n}-\mathrm{x})!\mathrm{x}!](1-\mathrm{p})^{\mathrm{n}-\mathrm{x}} \mathrm{p}^{\mathrm{x}} \\
& \text { Mean }=\mathrm{p}^{*} \mathrm{n}, \quad \sigma^{2}=\mathrm{pn}(1-\mathrm{p}), \quad \sigma^{2} / \text { mean }=(1-\mathrm{p})
\end{aligned}
$$

Need to know p \& n to evaluate each element of this distribution. Question: Toss three dice all at once, what is chance of getting a " 5 " ?
(the same as three throws of one die to get a " 5 " ... an experiment beckons) $n=3, x$ is number of $5^{\prime} s$

| $\mathrm{x}=0$ | $\mathrm{P}_{3}(0)=[3!/(3-0)!0!](1 / 6)^{0}(5 / 6)^{3}$ | 0.5787 |
| :--- | :--- | :--- |
| 1 | $\mathrm{P}_{3}(1)=[3!/(3-1)!1!](1 / 6)^{1}(5 / 6)^{2}$ | 0.3472 |
| 2 | $\mathrm{P}_{3}(2)=[3!/(3-2)!2!](1 / 6)^{2}(5 / 6)^{1}$ | 0.06944 |
| 3 | $\mathrm{P}_{3}(3)=[3!/(3-3)!3!](1 / 6)^{3}(5 / 6)^{0}$ | 0.00463 |

KIIR8


## Statistics \& Measurement - Models - $2 \mathrm{a}-$

Test random dice-roller app (https://xkcd.com/221)

```
int getRandomNumber()
    return 4; // chosen by fair dice roll.
    // guaranteed to be random.
}
```

$$
\begin{aligned}
& \text { Mean }=\mathrm{p} * \mathrm{n}=1 / 6 * 3=1 / 2 \\
& \sigma^{2}=\mathrm{p} \mathrm{n}(1-\mathrm{p})=1 / 6 * 3 *(5 / 6)=5 / 12
\end{aligned}
$$

| $\mathrm{x}=0$ $\mathrm{P}_{3}(0)=[3!/(3-0)!0!](1 / 6)^{0}(5 / 6)^{3}$ 0.5787 <br> 1 $\mathrm{P}_{3}(1)=[3!/(3-1)!1!](1 / 6)^{1}(5 / 6)^{2}$ 0.3472 <br> 2 $\mathrm{P}_{3}(2)=[3!/(3-2)!2!](1 / 6)^{2}(5 / 6)^{1}$ 0.06944 <br> 3 $\mathrm{P}_{3}(3)=[3!/(3-3)!3!](1 / 6)^{3}(5 / 6)^{0}$ 0.00463 |  |  |  |
| :--- | :---: | :---: | :---: |
| Note: $\Sigma \mathrm{P}_{\mathrm{n}}(\mathrm{x})=1$ |  |  |  |



## Statistics \& Measurement - Models - $2 \mathrm{a}-$

Test random dice-roller app


Virtual Dice
100 throws of 3 dice ...

$$
\begin{aligned}
& \text { Mean }=\mathrm{p} * \mathrm{n}=1 / 6 * 3=1 / 2 \\
& \sigma^{2}=\mathrm{pnn}(1-\mathrm{p})=1 / 6 * 3 *(5 / 6)=5 / 12
\end{aligned}
$$



| $x=0$ | $P_{3}(0)=[3!/(3-0)!0!](1 / 6)^{0}(5 / 6)^{3}$ | 0.5787 |
| :--- | :--- | :--- |
| 1 | $P_{3}(1)=[3!/(3-1)!1!](1 / 6)^{1}(5 / 6)^{2}$ | 0.3472 |
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© Note: $\Sigma \mathrm{P}_{\mathrm{n}}(\mathrm{x})=1$

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## Statistics \& Measurement - Models - $2 \mathrm{a}-$

Test random dice-roller app

100 throws of 3 dice ...


Virtual Dice
Mean $=\mathrm{p} * \mathrm{n}=1 / 6 * 3=1 / 2$
$\sigma^{2}=\operatorname{pn}(1-\mathrm{p})=1 / 6 * 3 *(5 / 6)=5 / 12$


Total of 3 Dice

| $\mathrm{x}=0$ | $\mathrm{P}_{3}(0)=[3!/(3-0)!0!](1 / 6)^{0}(5 / 6)^{3}$ | 0.5787 |
| :--- | :--- | :--- |
| 1 | $\mathrm{P}_{3}(1)=[3!/(3-1)!1!](1 / 6)^{1}(5 / 6)^{2}$ | 0.3472 |
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| 3 | $\mathrm{P}_{3}(3)=[3!/(3-3)!3!](1 / 6)^{3}(5 / 6)^{0}$ | 0.00463 |

O Note: $\Sigma \mathrm{P}_{\mathrm{n}}(\mathrm{x})=1$

KIIR8


## Statistics \& Measurement - Models -3-

(II) Fluctuation Models:
B) The Poisson distribution $(\mathrm{p} \rightarrow 0)$ and large n (many tries before success)

$$
P_{n}(x)=\left[n!(1-p)^{n-x} p^{x}\right] /(n-x)!x!\rightarrow P_{n}(x)=\left[n^{x}(1-p)^{n-x} p^{x}\right] / x!\text { Since } n!/ n-x!\sim n^{x}
$$

$$
P_{n}(x)=\left[n^{x} p^{x}(1-p)^{n-x}\right] / x!\quad \text { rearrange }
$$

$$
n^{x} p^{x}=(n p)^{x}=(\bar{x})^{x} \quad \text { also } \quad p=\bar{x} / n
$$

$$
P_{n}(x)=\frac{(\bar{x})^{x}}{x!}\left(1-\frac{\bar{x}}{n}\right)^{n-x}
$$

when $n \gg x \quad P_{\text {Poisson }}(x)=\frac{(\bar{x})^{x}}{x!} e^{-\bar{x}} \quad$ Only one parameter, the mean
$\sum P_{p}(x)=1 \quad \bar{x}=p n \quad \sigma^{2}=\bar{x}(1-p)=\bar{x}$
Asymmetric (theoretical) distribution with a tail on high side

## Statistics \& Measurement - Models - 3a-

(II) Fluctuation Models:
C) Example of Poisson Distribution: Easy variant of the "birthday problem:" what is the probability that at least one person in this room has the same birthday as me?

$$
\begin{aligned}
& P_{\text {Poisson }}(x)=\frac{(\bar{x})^{x}}{x!} e^{-\bar{x}} \quad n \gg x \\
& \bar{x}=p n \quad p=\frac{1}{365.25} \\
& P_{P}(x=0)=\frac{(\bar{x})^{0}}{0!} e^{-\bar{x}} \\
& P_{P}(x>0)=\sum_{x=1}^{n} P_{P}(x)
\end{aligned}
$$

| $p=$ | 0.002738 | $[1 / 365.25]$ |
| ---: | :---: | ---: |
| $n=$ | 92 |  |
| $\langle x>=p n=$ | 0.251882 |  |
| $\operatorname{xp}(-<x>)=$ | 0.777336 |  |
|  |  |  |
| $x$ | $P(x)$ |  |
|  |  |  |
| 0 | 0.777336 |  |
| 1 | 0.195797 |  |
| 2 | 0.024659 |  |
| 3 | 0.00207 |  |
| 4 | 0.00013 |  |
| 5 | $6.57 \mathrm{E}-06$ |  |
| 6 | $2.76 \mathrm{E}-07$ |  |

Statistics \& Measurement - Models - $4-$
(II) Fluctuation Models:
C) The Gaussian approximation, $\mathrm{p} \rightarrow 0, \mathrm{n} \gg 1 \&$ mean $=\mathrm{p}^{*} \mathrm{n}>20$

$$
P_{G}(x)=\frac{1}{\sqrt{2 \pi \bar{x}}} e^{-(\bar{x}-x)^{2} / 2 \bar{x}} \quad \text { or } \quad G(x)=\frac{1}{\sigma \sqrt{2 \pi}} e^{-(\bar{x}-x)^{2} / 2 \sigma^{2}}
$$

Symmetric Continuous distribution (one parameter) AKA chi-squared distribution:

$$
G(\chi)=\frac{2}{\sqrt{2 \pi}} e^{-\chi^{2} / 2} \quad \text { where } \chi=(\bar{x}-x) / \sigma
$$




## Statistics \& Measurement -Analysis -1-

(III) Analysis of data
A) Are fluctuations in a set of N -values consistent with statistical accuracy? Measure: $\mathrm{x}_{\mathrm{e}}$ and $\mathrm{s}^{2} \quad$ Model: mean gives $\sigma^{2} \ldots$ thus the test: Is $\mathrm{s}^{2}=\sigma^{2}$ ?

Define a statistic $\chi$ in terms of measurable values that will provide a simple test.

$$
\begin{aligned}
& \chi^{2}=\sum_{i=1}^{N}\left(\frac{\overline{x_{e}}-x}{s}\right)^{2}=\sum_{i=1}^{N} \frac{\left(\overline{x_{e}}-x\right)^{2}}{s^{2}}=\sum_{i=1}^{N} \frac{\left(\overline{x_{e}}-x\right)^{2}}{\overline{x_{e}}} \\
& \chi^{2}=\frac{\sum_{i=1}^{N}\left(\overline{x_{e}}-x\right)^{2}}{\overline{x_{e}}}=\frac{s^{2}(N-1)}{\overline{x_{e}}} \quad \rightarrow \quad \frac{\chi^{2}}{(N-1)}=\frac{s^{2}}{\overline{x_{e}}}
\end{aligned}
$$

But in a "good" data set with large $\mathrm{N}: \mathrm{s}^{2}=\sigma^{2}=$ mean

$$
\therefore \quad \frac{\chi^{2}}{(N-1)}=1 \quad \text { or } \quad \chi^{2}=(N-1)
$$

## Statistics \& Measurement - Analysis -2-

(III) Analysis of data
B) Only one measurement, estimate uncertainty?

There is only one measurement of an integer quantity, strictly speaking, you are out of luck.
However, one can posit that it must be the mean, and $\sigma^{2}=$ mean One further assumes that the distribution is symmetric: $x+/-\sigma$ Fractional error: $\sigma / \mathrm{x}=\sqrt{x}^{\mathrm{x}} / \mathrm{x}=1 / \sqrt{x}^{\mathrm{x}}$
(IV) Measurements in the presence of Background (itself measureable) (1) measure background (B); (2) measure source + background ( $\mathrm{S}+\mathrm{B}$ ). $\mathrm{S}=(\mathrm{S}+\mathrm{B})-\mathrm{B} \ldots$ nothing new here but there are two contributions to error. How should the time be allocated to give minimum uncertainty in S ie $s_{\mathrm{S}}$ ?

Simplest case, constant rates the minimum in $s_{\mathrm{S}}$ comes when:

$$
\frac{\text { time }_{S+B}}{\text { time }_{B}}=\sqrt{\frac{S+B}{B}}=\sqrt{\frac{S}{B}+1}
$$

B diminishes in importance for large $S$


## Statistics \& Measurement - time distribution

(V) Time between random events, the Interval distribution:
A) The product of the probability that nothing happens for some length of time, $t$, times the probability that the next event occurs in the small interval, dt.


$$
I_{1}(t) d t=\left[P_{P}(x=0)\right][r d t] \text { where } \mathrm{r} \text { is average rate }
$$

$$
I_{1}(t) d t=\frac{(\bar{x})^{0}}{0!} e^{-\bar{x}}[r d t] \quad \text { where } \quad \bar{x}=r^{*} t
$$

$$
I_{1}(t) d t=e^{-r t} r d t
$$



Note the most-probable time between events occurs at $\mathrm{rt}=0$, note $\mathrm{r}>0 \ldots$
The average time between events

$$
\bar{t}_{1}=\frac{\int_{0}^{\infty} t I_{1}(t) d t}{\int_{0}^{\infty} I_{1}(t) d t}=\frac{\int_{0}^{\infty} t r e^{-r t} d t}{1}=\frac{1}{r} \quad(r>0)
$$

## Statistics \& Measurement - time distribution

(V) Time between random events, the Interval distribution:
B) Some people like to "scale-down" high counting rates by a factor, N. Similar arguments give the distribution of the N -th event as:

$$
\begin{aligned}
& I_{N}(t) d t=P(N-1) r d t \\
& I_{N}(t) d t=\frac{(r t)^{N-1}}{(N-1)!} e^{-r t} r d t
\end{aligned}
$$


which is a curve that has a peak near the value $(\mathrm{rt})=\mathrm{N}-1$
[find most-probable time from $\mathrm{dI}_{\mathrm{N}} / \mathrm{dt}=0 \ldots \mathrm{t}_{\mathrm{mp}}=(\mathrm{N}-1) / \mathrm{r}$ ]
and an average time between scaled events:

$$
\bar{t}_{N}=\frac{\int_{0}^{\infty} t I_{N}(t) d t}{\int_{0}^{\infty} I_{N}(t) d t}=\frac{N}{r} \quad(r>0)
$$

## Statistics \& Measurement - time distribution

(V) Time between random events, the Interval distribution
C)Examples of Interval Distribution from nuclear physics:

1) One of the early results from the Sudbury Neutrino Observatory (SNO) was that 1968 charged-current neutrino events were observed in 306.4 days of operation. One concern on any given day in low counting rate experiments is that the detector has failed. What is the probability that no events were observed on any given day during this run?

> Time passes until "evt occurs"
> Probability of "event" in 1day
> Probability of "not" in 1 day
2) The confirmation in 2013 of Element 115 claimed to have measured 30 atoms in a "three week run". Similarly, what is the probability that this experiment went 1 day without observing an event?

## Week 4: Chap. 4 Basic Detector Principles

## General use of Statistical Distributions

## Basic Detector Principles

-- Current Mode
-- Pulse Mode
--- resolution
---- Fano Factor
--- efficiency
--- dead time

## Ion Chambers



